

# Multiresolution approach for period determination on unevenly sampled data

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## ABSTRACT

In this paper we present a multiresolution-based method for period determination that is able to deal with unevenly sampled data. This method allows us to detect superimposed periodic signals with lower signal-to-noise ratios than in classical methods. This multiresolution-based method is a generalization of the wavelet-based method for period detection that is unable to deal with unevenly sampled data, presented by the authors in an earlier paper. This new method is a useful tool for the analysis of real data and, in particular, for the analysis of astronomical data.

**Key words:** methods: data analysis – methods: numerical – stars: variables: other – X-rays: binaries.

## 1 INTRODUCTION

The detection of periodic signals in astronomical data has usually been addressed by classical Fourier-based or epoch folding methods. These methods have different problems when dealing with non-sinusoidal periodic signals or with very low signal-to-noise ratios. When the analysed data set contains several periodic signals, the behaviour of classical period-determination methods depends on intrinsic signal characteristics (see, for example, Laffer & Kinman 1965; Jurkevich 1971; Lomb 1976; Stellingwerf 1978; Scargle 1982, 1989; Roberts, Lehár & Dreher 1987; Press & Rybicky 1989). The reader is referred to the introduction of Otazu et al. (2002) (hereafter Paper I) for a general discussion. To avoid this problem, we presented there, as a preliminary step, a wavelet-based approach that only works with evenly time-sampled data.

In astronomy, however, this is not the usual situation, since data are mostly acquired on irregular intervals of time. In such a case there are two possibilities: resample the data into a new evenly sampled data set, or use a method able to deal with the original unevenly sampled data set. In the first case we are forced to modify the original data, which necessarily implies a loss of information. Moreover, this is not always possible if the temporal gaps are larger than some of the periods present in the data. In order to avoid these problems, a technique capable of dealing with unevenly sampled data is needed.

The present paper is a natural extension of Paper I that allows us to work on unevenly time-sampled data. We show how the methodology of multiresolution decomposition (similar to the wavelet decomposition philosophy) is very well suited to this problem, since it is completely oriented towards decomposing functions into several frequential characteristics.

As in Paper I, the main objective is to isolate every signal present in our data and to analyse them separately, avoiding their mutual influences. In Section 2 we outline some concepts in multiresolution analysis and their similarities with wavelet theory that are relevant to the stated problem. In Section 3 we propose an algorithm to detect each of the periodic signals present in a data set by combining multiresolution analysis decomposition with classical period determination methods. In Sections 4 and 5 we present some examples of synthetic data we used to test the algorithm and the results we obtained. We summarize our conclusions in Section 6.

## 2 MULTIREOLUTION ANALYSIS

Multiresolution decomposition introduces the concept of the presence of details between successive levels of resolution. Many wavelet decomposition algorithms are based on multiresolution analysis schemes (Chui 1992; Daubechies 1992; Meyer 1993; Kaiser 1994; Vetterli & Kovacevic 1995; Mallat 1999; Starck & Murtagh 2002), and some astronomical applications using wavelets for timing analysis have been reported (Szatmáry, Vinkó & Gál 1994; Foster 1996; Ribó et al. 2001; Polygiannakis, Preka-Papadema & Moussas 2003). In fact, all these methods use the same philosophy and the obtained results can be interpreted in the same way. However, wavelet theory presents some constraints on

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mathematical functions. These constraints are not respected in all multiresolution decomposition schemes. Therefore, when we are using a certain multiresolution decomposition algorithm that fulfils the wavelet constraints, we are obtaining a wavelet decomposition. In contrast, when a given multiresolution decomposition algorithm violates these wavelet constraints, we are obtaining a result similar to, but which is not, a wavelet decomposition.

As discussed in Paper I, we note that there are wavelet approaches that are based on approximations of a continuous wavelet transform and on the subsequent study of wavelet space coefficients (see, e.g. Szatmáry et al. 1994), which are able to deal with unevenly sampled data sets. However, these algorithms present a non-direct inverse wavelet transform, in the sense that the search for periodicities is based on the fit between the wavelet base function profile and the signal profile, and therefore on the values of the wavelet transform coefficients, which depend on the wavelet base used. Moreover, the period analysis has to be performed on wavelet coefficient space but, since it is usually decimated, accurate period detection is a difficult task. The multiresolution decomposition scheme we use in this work performs the decomposition on temporal space, which allows us to find accurate values for periodicities.

### 2.1 A multiresolution analysis algorithm

In order to obtain a multiresolution decomposition for signals, an algorithm to decompose the signal into frequency planes can be defined as follows. Given a signal  $p$  we construct the sequence of approximations:

$$p_1 = F_1(p), \quad p_2 = F_2(p_1), \quad p_3 = F_3(p_2), \dots, \quad (1)$$

performing successive convolutions with Gaussian filters  $F_i$ .

It is important to note the difference between this sequence of convolutions and that used in Paper I. In the latter we were dealing with a discrete convolution mask, and hence forced to work with evenly spaced data. In contrast, the continuous nature of the convolution functions used in the present paper allows us to work with unevenly sampled data.

Similarly to the wavelet planes, the multiresolution frequency planes are computed as the differences between two consecutive approximations  $p_{i-1}$  and  $p_i$ . Letting  $w_i = p_{i-1} - p_i$  ( $i = 1, \dots, n$ ), in which  $p_0 = p$ , we can write the reconstruction formula:

$$p = \sum_{i=1}^n w_i + p_r. \quad (2)$$

In this representation, the signals  $p_i$  ( $i = 0, \dots, n$ ) are versions of the original signal  $p$  at increasing scales (decreasing resolution levels),  $w_i$  ( $i = 1, \dots, n$ ) are the multiresolution frequency planes and  $p_r$  is a residual signal (in fact  $n = r$ , but we explicitly replace  $n$  by  $r$  to express clearly the concept of *residual*). In our case, we are using a dyadic decomposition scheme. This means that the standard deviation of the Gaussian function associated with the  $F_i$  filter is  $\sigma_i = 2\sigma_{i-1}$ . Thus, similarly to the wavelet approach, the original signal  $p_0$  has double resolution compared to  $p_1$ , and so on. All these  $p_i$  ( $i = 0, \dots, n$ ) signals have the same number of data points as the original signal  $p$ .

Since  $\sigma_{i+1}$  depends on  $\sigma_i$ , a value for  $\sigma_0$  has to be carefully chosen for every data set. It has to be fixed considering a likely minimum value for the time duration of the features and the characteristic time sampling of the data set, in order to include a significant number of points on which to perform the convolutions. Too small values do not accurately describe feature profiles, and suffer from

poor or noisy data. In contrast, too large values reduce the noise effect by integrating a lot of data points, but may ignore interesting high-frequency features. Hence, a first analysis of data has to be performed in order to obtain a useful initial  $\sigma_0$  value.

We have used the same notation as in the wavelet decomposition described in Paper I because, as explained above, the idea of these multiresolution planes is similar to the wavelet planes.

We note that this particular decomposition scheme that uses a Gaussian kernel can also be interpreted as a scale-space filtering (Baubaud et al. 1986; Witkin 1994; Sporring et al. 1997) or as a particular case of more general image diffusion approaches (Lindeberg 1990; Perona & Malik 1990). Smoothed data sets  $p_i$  can be interpreted as diffused scale-space images, and the difference between them as the details at different scales.

### 3 PERIOD-DETECTION ALGORITHM

We propose to apply this multiresolution analysis algorithm to solve our initially stated problem: to isolate each of the periodic signals contained in a set of unevenly sampled data and study them separately.

In order to do so, we proceed as in Paper I, and the period-detection algorithm we propose is as follows:

- (i) choose values for  $\sigma_0$  and  $n$ ; decompose the original signal  $p$  into its multiresolution frequency planes  $w_i$  ( $i = 0, \dots, n$ );
- (ii) detect periods in each of the  $n$  obtained frequency planes  $w_i$ .

The Phase Dispersion Minimization (PDM) (Stellingwerf 1978) and CLEAN (Roberts et al. 1987) methods are used to detect periods in the original data and in every multiresolution frequency plane. In Paper I we described several undesirable effects of the PDM and CLEAN methods on data with superimposed signals, as well as the advantages of using multiresolution-based methods over classical methods.

Hereafter, and for notational convenience, the multiresolution-based PDM and CLEAN methods will be called MRPDM and MRCLEAN, respectively.

### 4 SIMULATED DATA

In order to check the benefit of applying MRPDM versus PDM, or MRCLEAN versus CLEAN, we proceeded similarly as in Paper I by generating and analysing several sets of simulated data containing two superimposed periodic signals. Each data set is composed of a high-amplitude primary sinusoidal function and a secondary low-amplitude Gaussian function. Finally, we added white Gaussian noise to this combination of signals. We increased the value of the noise standard deviation,  $\sigma$ , up to the value where detection of periodic signals became statistically insignificant in both the classical and multiresolution-based methods.

The primary signal is intended to simulate variable sources with a pure sinusoidal intensity profile (like precession of accretion discs), and the secondary, burst-like events (like pulses or eclipses) superimposed on it. We note that in Paper I we also studied the superposition of two sinusoidal functions, the so-called sine+sine case. However, here we have directly focused on the more realistic situation of the so-called sine+Gaussian case, where the difference between the classical and the multiresolution-based methods is more critical (see Paper I).

The characteristics of the signals are as follows.

- (i) Each signal is generated as an unevenly spaced data set. Its time sampling has been taken from observations of the X-ray

binary LMC X-1 by the All Sky Monitor onboard the *RXTE* satellite (Levine et al. 1996). We have used an observation period which has 8270 measurements during 679 d.

(ii) The high-amplitude sinusoidal function has an amplitude equal to 1 and a period of 108.5 d.

(iii) The amplitudes of the low-amplitude periodic Gaussian function are 0.1 and 0.5.

(iv) The periods used for the secondary function are 13.13 and 23.11 d.

(v) We have used two values for the full width at half-maximum (FWHM) of the Gaussian signal, corresponding to 2 and 6 d, respectively.

In the first four columns of Table 1 we present the parameters used to generate each simulated data set.

## 5 RESULTS

We recall that the simultaneous use of two independent methods, such as CLEAN and PDM, is usually applied to discriminate false period detections from true ones. A similar procedure can be used with each one of the multiresolution planes in the MRPDM and MRCLEAN methods. Therefore, when comparing the behaviour of these different methods, we have to compare the usual PDM–CLEAN method combination for period estimation prior to the new MRPDM–MRCLEAN combination.

Taking into account the characteristics of the simulated data we have chosen  $\sigma_0 = 1$  d. As in Paper I, the primary period (108.5 d) is always detected by all methods, and does not appear in Table 1. In this table, the last four columns show the detected low-amplitude periods for each data set using the PDM, CLEAN, MRPDM and MRCLEAN methods, respectively. A dash is shown when a period is not detected, and a question mark when the detection is difficult or doubtful. When a period is found in the multiresolution-based methods, we also show in parentheses the multiresolution planes where it is detected.

We must note that the use of two different FWHM for the Gaussian, combined with two different periods (13.13 and 23.11 d), gives four different profiles. Hence, the phase duration of the burst-like event ranges from very low to relatively high values in the following order: FWHM = 2 and period = 23.11, FWHM = 2 and period = 13.13, FWHM = 6 and period = 23.11, and finally FWHM = 6 and period = 13.13.

In view of the results displayed in Table 1 we can make the following comments.

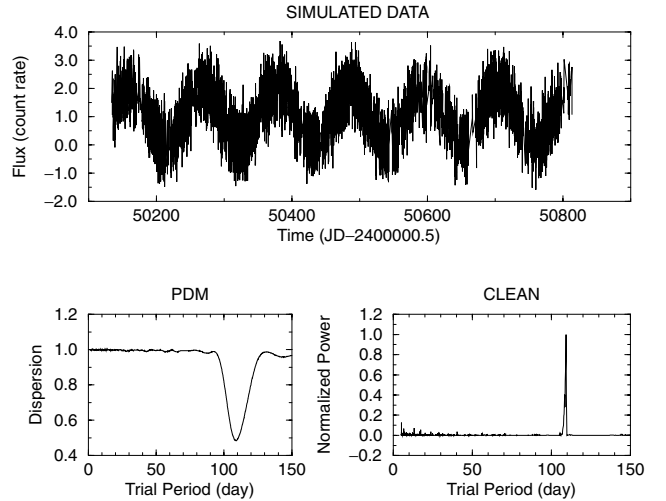
(i) In all methods, with high noise-to-signal ratios the detected periods are slightly different from the simulated periods.

(ii) There is better performance of CLEAN over PDM. We must note that when the FWHM is only 2 d, PDM never detects the secondary period. Only with FWHM = 6 d, and a relatively high amplitude (0.5), can PDM detect the low-amplitude periodic signals.

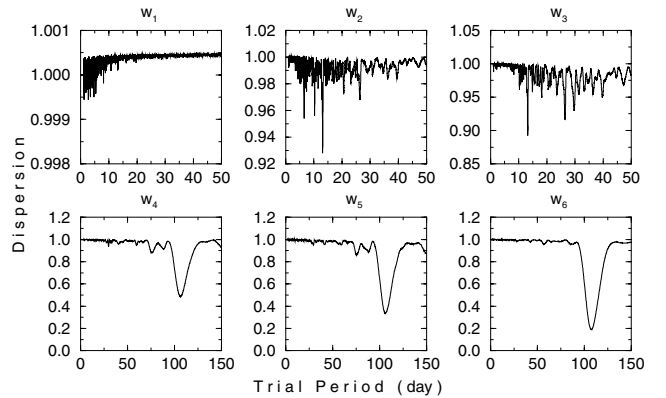
(iii) As the noise increases, the detection starts to fail in the lower multiresolution planes (higher frequencies), and only the higher ones (lower frequencies) are noise-free enough to allow period detection.

(iv) MRPDM and MRCLEAN perform better than or similar to the PDM and CLEAN methods (but see the exception below). When CLEAN marginally detects the secondary period, MRPDM, and most of the time MRCLEAN, have no problems in detecting it, and they work properly even with higher noise. In the MRPDM case, the results are always better than with PDM.

(v) In all cases with FWHM = 2, the MRPDM performance is much better than MRCLEAN, because the signal is clearly non-sinusoidal. In



**Figure 1.** Top: simulated data of a Gaussian with 13.13-d period, a FWHM of 6.0 d, amplitude = 0.1 and  $\sigma_{\text{noise}} = 0.6$ , superimposed on the sinusoid with 108.5-d period and amplitude=1.0. Bottom: PDM and CLEAN outputs of this data set.



**Figure 2.** MRPDM output for each wavelet plane of the data at the top of Fig. 1.

the FWHM = 6 cases, MRPDM is only slightly better than MRCLEAN, since the signals are closer to a sinusoidal profile.

(vi) For a given amplitude of the Gaussian signal, the maximum noise-to-signal ratio achieved with MRPDM and MRCLEAN increases with the phase duration of the FWHM.

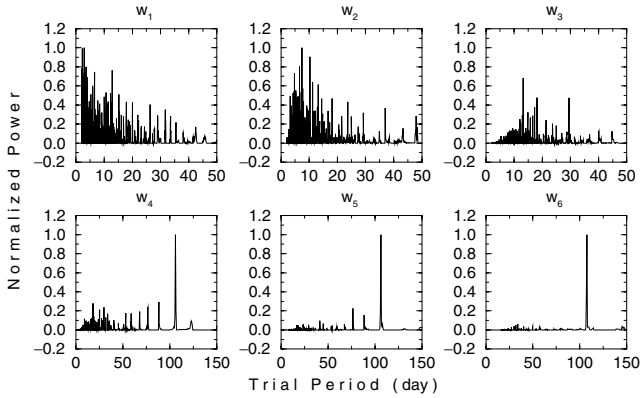
The only exception to (iv) is for the most extreme of the simulated cases, i.e. the one with the lower amplitude, lower FWHM value and longer period. However, we note that the period detected by CLEAN is slightly different from the simulated period.

All these results are very similar to those shown in table 2 of Paper I. Nevertheless the maximum noise-to-signal ratios achieved in the present cases are around 2.5 times higher. This can be explained because, although the time span of the data sets used here is around 1.5 times smaller, the number of points per unit time is around 12 times higher than in Paper I.

Finally, and for illustrative purposes, we show in Fig. 1 the simulated data set generated with the following: 13.13-d period, FWHM = 6.0 d and amplitude = 0.1 with  $\sigma_{\text{noise}} = 0.6$ . The outputs of PDM and CLEAN are also shown. None of these methods is able to detect the 13.13-d period. We show in Fig. 2 the outputs from MRPDM. The simulated period is detected, with its corresponding subharmonics,

**Table 1.** Periods, in days, detected in the data sets. The first four columns are the parameters used for the simulated data. A dash is shown when a period is not detected, and a question mark when the detection is difficult or doubtful. When a period is indicated in the multiresolution-based methods, we also show in parentheses the multiresolution planes where it is detected (using  $\sigma_0 = 1$  d).

FWHM	Period	Amplitude	$\sigma_{\text{noise}}$	PDM	CLEAN	MRPDM	MRCLEAN		
2	13.13	0.1	0.0	–	13.13	13.13 (1,2)	13.13 (1,2)		
			0.1	–	13.13	13.13 (1,2)	13.13 (1,2)		
			0.15	–	13.13	13.13 (1?,2)	13.13 (1?,2)		
			0.2	–	13.15?	13.13 (1?,2)	13.13 (2)		
			0.25	–	–	13.14 (1?,2)	–		
			0.3	–	–	13.14 (2)	–		
			0.35	–	–	13.14 (2?)	–		
			0.4	–	–	–	–		
		0.5	0.0	–	13.13	13.13 (1,2,3)	13.13 (1,2,3)		
			0.5	–	13.13	13.13 (1?,2,3)	13.13 (1?,2,3)		
			1.0	–	13.14?	13.13 (2,3)	13.13 (2,3)		
			2.0	–	–	13.14 (2,3)	13.14 (3?)		
			2.25	–	–	13.14 (2?)	–		
			2.5	–	–	–	–		
	–		–	–	–	–			
	23.11	0.1	0.0	–	23.13	23.11 (1,2?)	–		
			0.1	–	23.19	23.11 (2?)	–		
			0.15	–	–	–	–		
			0.5	0.0	–	23.12	23.11 (2?,3,4)	23.11 (3?)	
				0.5	–	23.11?	23.11 (2?,3,4)	–	
				1.0	–	–	23.11 (2?,3,4)	–	
		1.25		–	–	23.11 (2?,3,4)	–		
		1.5	–	–	–	–			
		6	13.13	0.1	0.0	–	13.13	13.13 (1,2,3)	13.13 (1,2,3)
					0.1	–	13.14	13.13 (1,2,3)	13.13 (1,2,3)
					0.2	–	13.14	13.13 (1?,2,3)	13.13 (1?,2,3)
					0.3	–	13.14	13.13 (2,3)	13.13 (2,3)
					0.4	–	13.15?	13.14 (2,3)	13.14 (3)
0.6					–	–	13.14 (2,3)	13.14 (3?)	
0.8	–				–	13.15 (3)	13.15 (3?)		
0.9	–				–	–	–		
0.5	0.0			13.13	13.13	13.13 (1,2,3)	13.13 (1,2,3)		
	0.5			13.13	13.12	13.13 (1,2,3)	13.13 (1,2,3)		
	1.0			13.13	13.14	13.13 (1?,2,3)	13.13 (1?,2,3)		
	2.0			13.13	13.13	13.13 (2,3)	13.13 (2,3)		
	3.0			13.13?	13.11?	13.13 (2?,3)	13.13 (3)		
	4.0			–	–	–	–		
23.11	0.1		0.0	–	23.12	23.11 (2,3)	23.11 (2,3)		
			0.1	–	23.12	23.11 (2,3)	23.11 (2,3)		
			0.2	–	23.12	23.11 (2?,3)	23.11 (2?,3)		
			0.3	–	23.12	23.11 (3)	23.11 (3)		
		0.4	–	23.12?	23.11 (3?)	23.11 (3)			
		0.5	–	–	23.11 (3?)	–			
		0.6	–	–	–	–			
		0.5	0.0	23.11	23.11	23.11 (2?,3,4,5)	23.11 (3?,4,5)		
	0.5		23.11	23.11	23.11 (2?,3,4,5)	23.11 (4,5)			
	1.0		23.11	23.11	23.11 (3,4,5)	23.11 (4,5?)			
	2.0		23.11?	23.12	23.11 (3?,4,5)	23.11 (4,5?)			
	2.5		23.11?	23.12	23.11 (4,5?)	23.11 (4,5?)			
	3.0		–	–	23.12 (4)	23.11 (4)			
	3.5	–	–	23.12 (4?)	–				
4.0	–	–	–	–					



**Figure 3.** MRCLEAN output for each wavelet plane of the data at the top of Fig. 1.

in the multiresolution planes  $w_2$  and  $w_3$ . The MRCLEAN outputs, shown in Fig. 3, reveal a marginal detection of the 13.13-d period in multiresolution plane  $w_3$ . We note that we would not consider this detection as a true one when taken alone. However, since the same period is clearly detected in two multiresolution planes of MRPDM, we can establish the existence of this period in the analysed data set.

## 6 CONCLUSIONS

In this paper we have presented a multiresolution-based method for period determination able to deal with unevenly sampled data. This constitutes a significant improvement with respect to the wavelet-based method presented in Paper I, which is unable to deal with unevenly sampled data. The overall performance of the present method is similar to the wavelet-based one, in the sense that it allows us to detect superimposed periodic signals with lower signal-to-noise ratios than in classical methods. We stress that one advantage of the present method over classical methods is the simultaneous detection of a period in more than one multiresolution plane, allowing us to improve the confidence of a given detection. Moreover, since here we are not forced to lose or modify the information when averaging or interpolating the original data, we can reach higher noise-to-signal ratios than in the wavelet-based method described in Paper I.

We note that the multiresolution decomposition scheme that we have used can be interpreted as a particular case of scale-space filtering. In order to improve isolation of periodic features, more general approaches could be used to perform this decomposition. In this context, the anisotropic diffusion schemes proposed by Perona & Malik (1990) could be useful if properly tuned.

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